

Maintaining integrity, performance and safety of the road infrastructure, through autonomous robotized solutions and modularization

Dr Thierry GOGER - FEHRL

InfraROB. Project overview

• Our resources



<https://cordis.europa.eu/project/id/955337/en>

• Our Consortium

Universidade de Vigo



Universidade do Minho



TECHNISCHE
UNIVERSITÄT
DARMSTADT

Technology
Arts Sciences
TH Köln



University of Vigo
(Coordinator), INSITU

Universidade do Minho

TUDa, THKöln, TPA, MOBA

RINA-C, NTS, BRUSSI, AIPSS,
Sapienza Università, ROMATre

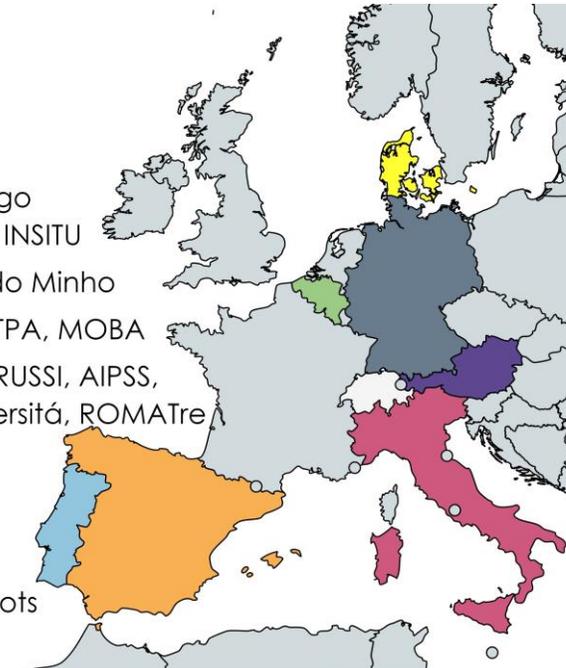
FEHRL, CECE

IMC

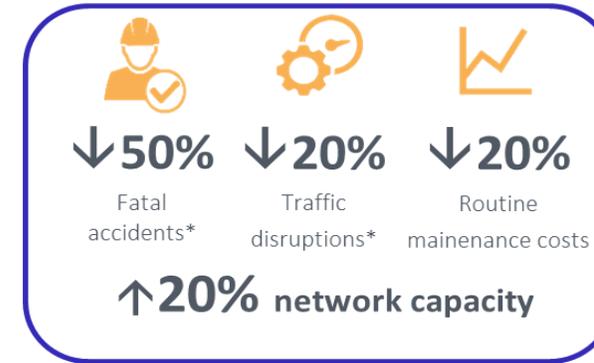
ASFINAG

TinyMobileRobots

Created with mapchart.net

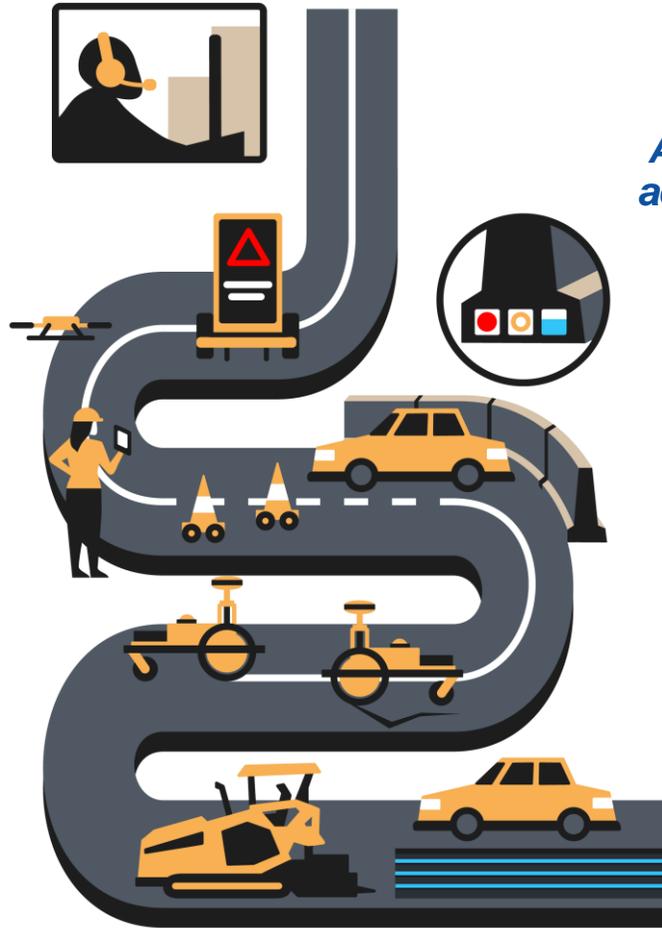


InfraROB. Project overview



• Our objectives (Technological Areas)

- TA5**
Upgrading of Management Systems to ensure safer operations and maintenance
- TA4**
Collaborative operation of safety cone robots and RPAS for work zone segmentation and signalling
- TA2**
Autonomous robotized machinery for the routine or periodic maintenance of the pavement



By focusing on the roadbed and, particularly, on ROADS PAVED WITH ASPHALT, InfraROB entails advancements across 5 strictly interrelated technological areas (TA)

- TA3**
Modularization of road construction/upgrade through industrial prefabrication
- TA1**
Autonomous robotized machinery for construction, upgrade and large maintenance interventions

InfraROB. Results

Actual achievements

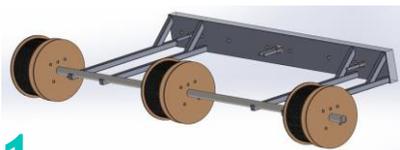
01



AUTONOMOUS AND AUTONOMOUSLY-WORKING ROAD CONSTRUCTION TRAIN (PAVER, FEEDER, ROLLER)

30%

01.1



DEVICE FOR THE AUTOMATED LAYDOWN OF FOS CABLES DURING THE PAVING PROCESS



-10%

02



PROTOTYPE OF AUTONOMOUS ROBOTIZED HEAD TO REPAIR POTHOLES AND CRACKS (ASPHALT ROUTINE MAINTENANCE)

40%

03

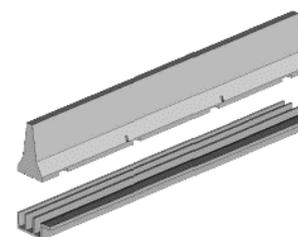


AUTONOMOUSLY-WORKING LINE MARKING ROBOT (COLD PAINT)



10%

04



MULTI-FUNCTIONAL PRECAST CONCRETE ELEMENT (ROADSIDE ELEMENT)



30%

InfraROB. Results

Actual achievements

05



COLLABORATIVE OPERATION BETWEEN SAFETY CONE ROBOTS AND RPAS FOR ENHANCED WORK ZONE SEGMENTATION AND SIGNALLING

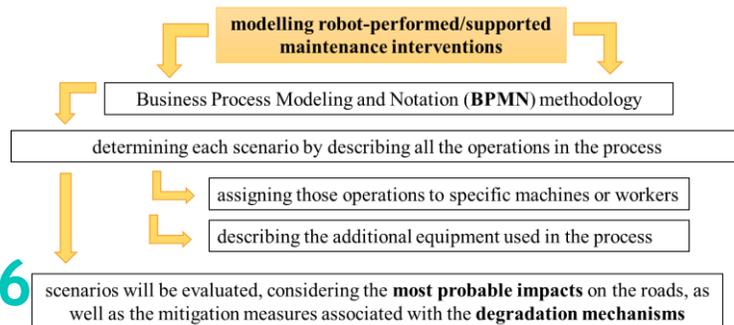
07



DIGITAL-TWIN BASED APPLICATION FOR PMS (PAVEMENT MANAGEMENT SYSTEM)

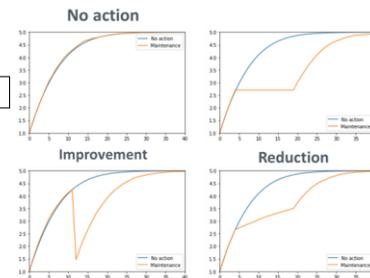
20%

06



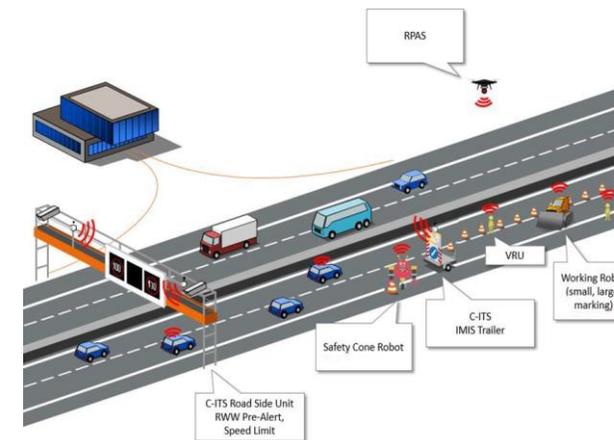
PMS UPGRADE (TAKING INTO ACCOUNT THE INTRODUCTION OF ROBOTICS)

20%



30%

08



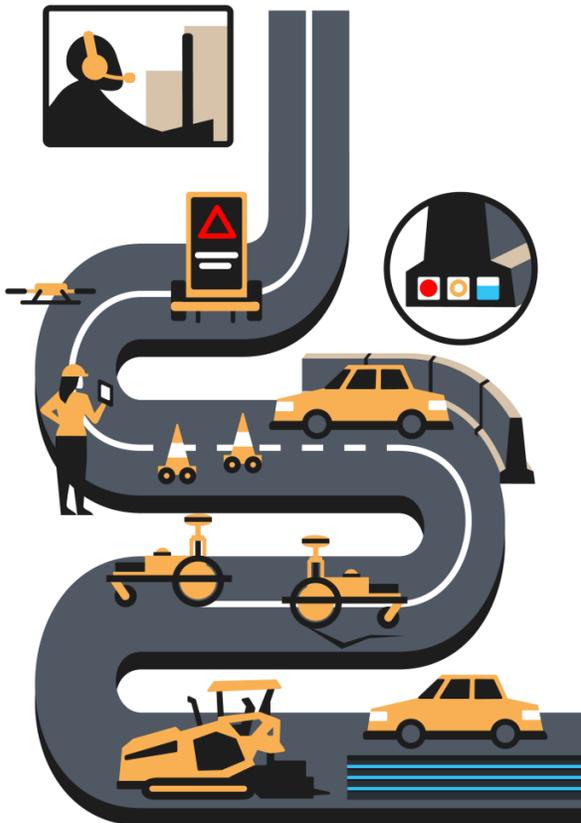
TMS UPGRADE (TAKING INTO ACCOUNT THE INTRODUCTION OF ROBOTICS) (TRAFFIC MANAGEMENT SYSTEM)

20%

InfraROB. Results

PATENT	IPR PROTECTION	PRODUCT AND SERVICE TO THE MARKET	PRODUCT TO THE MARKET	SERVICE TO THE MARKET
Autonomous paver sensors-control system (pending)	Asphalt mixture to repair of small potholes and cracks by the additive producer	Autonomous line marking robot & support RPxS system for monitoring work zones Upgrade of existing PMS solutions FOS solution for pavement damage detection	Multi-functional precast concrete element	Digital twin-based add-on application

InfraROB. Expected impact



- 

Upgrade of management systems for decision-making taking into account the introduction of robotics
- 

Autonomous robotized solution for work zone segmentation and signalling (drone based)
- 



Autonomous robotized interventions and modular solutions

		
↓50%	↓20%	↓20%
Fatal accidents*	Traffic disruptions*	Routine maintenance costs
↑20% network capacity		

SMART, GREEN, INTEGRATED TRANSPORT

VISION ZERO (EU Road Safety Policy Framework 2021-2030)

DIGITAL EUROPE (skills, business opportunities, infrastructure solutions)

InfraROB. Expected impact

• Communication, dissemination, exploitation

740

VISITS TO THE PROJECT WEBSITE

330

FOLLOWERS IN THE SOCIAL MEDIA



CECE Digitalisation Task-Force
CECE Product Group



Ciclo di seminari
"Strade, opere pubbliche e
mobilità sicura e sostenibile per il
buon governo del territorio"
5° Seminario
Sicurezza e sostenibilità
4 luglio 2022



>10

WORKSHOPS and OTHER ACTIVITIES/EVENTS



Atlántico FARO DE VIGO

5

PRESS RELEASES/PUBLICATIONS

Cross projects
cooperation



infrarobproject.com



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company/infrarob



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>5

SCIENTIFIC PAPERS SUBMITTED



FTRM 23

FEHRL Infrastructure Research Meeting

25 - 26 April 2023



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